# **Deep learning for measuring behavior**

Mathis Group for Computational Neuroscience and AI We develop computer vision and machine learning tools for the analysis and quantification of **behavior** including **pose estimation**, animal re-identification, action segmentation...

Join us and Mackenzie Mathis' lab in Geneva!

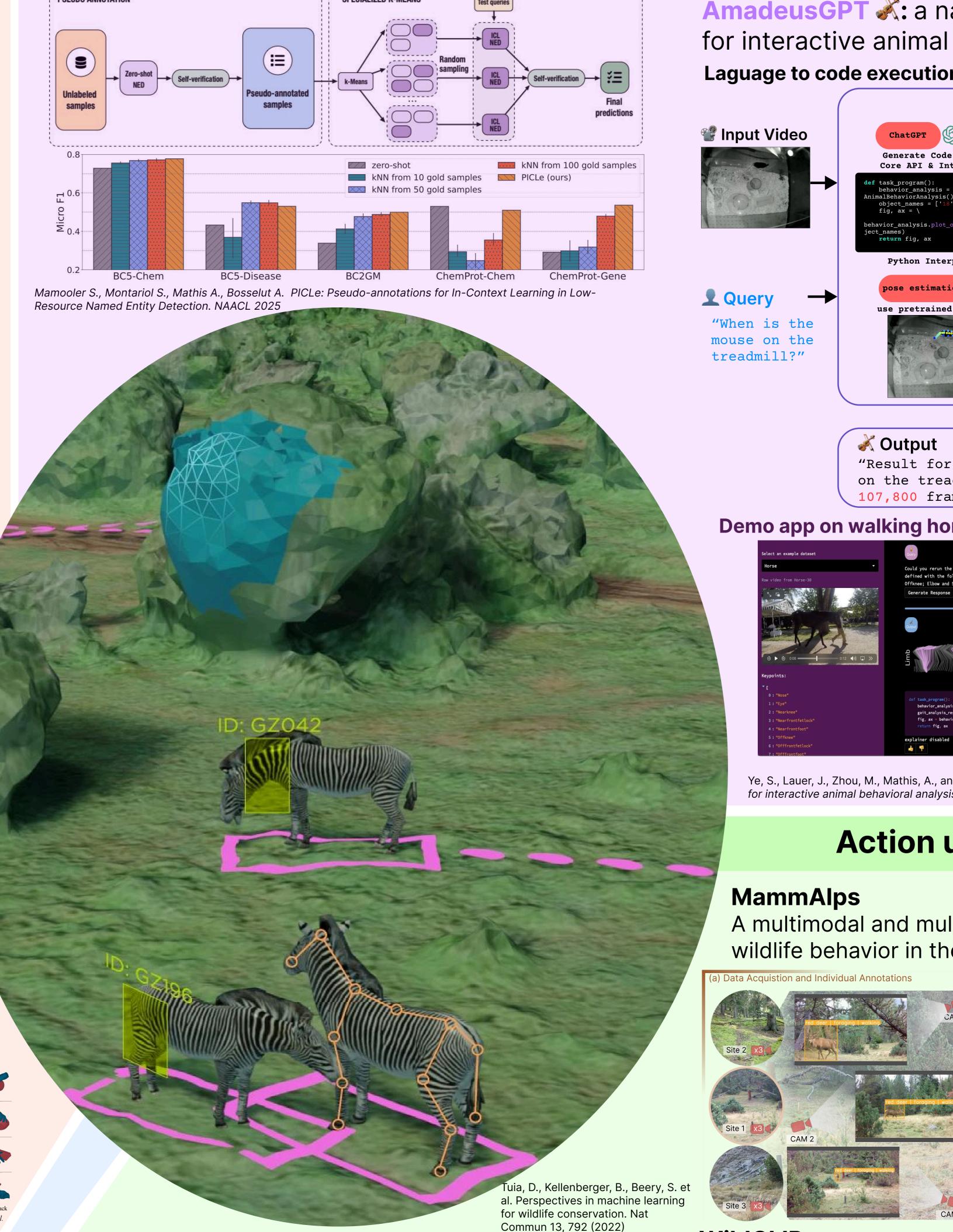


## **Pose estimation**



DeepLabCut: a software package for animal pose estimation

**DLC:** Efficient deep learning for single and multi-animal pose tracking and identification **PICLe:** Pseudo-annotations for In-Context Learning in Low-Resource Named Entity Detection

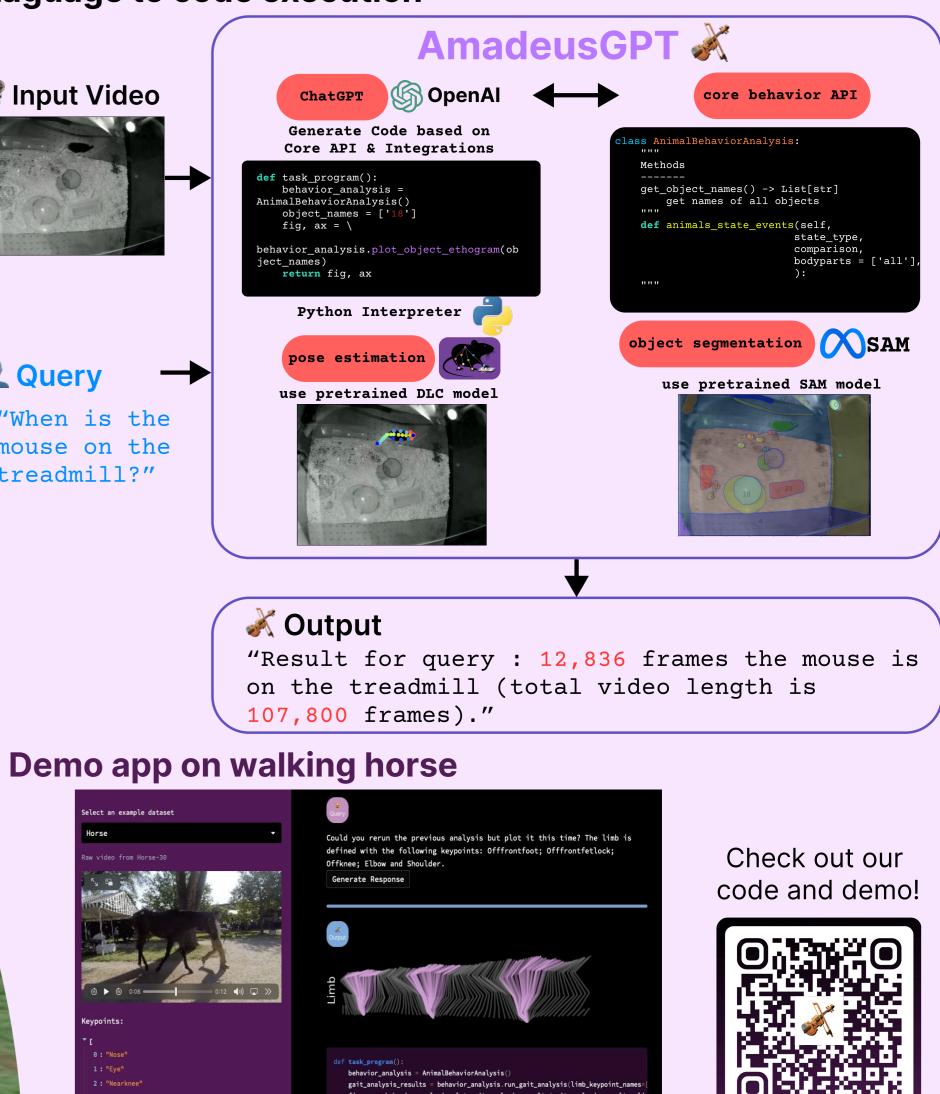


# **AI4Science with language models**



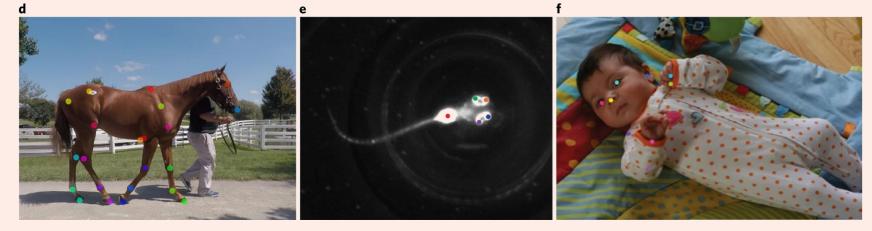
**AmadeusGPT «:** a natural language interface for interactive animal behavioral analysis

Laguage to code execution









Mathis, A., et al. "DeepLabCut: markerless pose estimation of user-defined body parts with deep learning." Nature neuroscience 21.9 (2018): 1281-1289. Nath, T., et al. "Using DeepLabCut for 3D markerless pose estimation across

species and behaviors." Nature protocols 14.7 (2019): 2152-2176. Lauer, J., et al. "Multi-animal pose estimation, identification and tracking with

DeepLabCut." Nature Methods 19.4 (2022): 496-504.

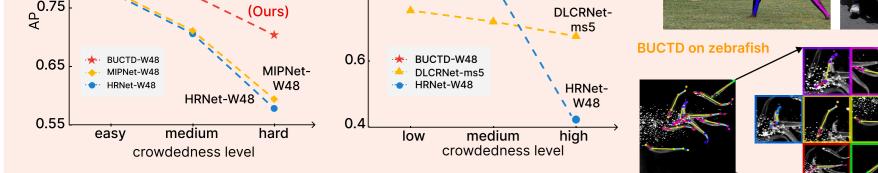
**BUCTD**: Overcoming the detection information bottleneck and ambiguity in pose estimation

**Bottom-Up Conditioned Top-Down (BUCTD) method** Comparison on CrowdPose Top-down: HRNet-W48 stage1: object and pose detection stage2: pose estimation #params GFLOP predictions HigherHR.-W32 28.6M 47.9 DEKR 28.6M 44.5 CID 29.4M 43.2 Human benchmark - CrowdPose Animal benchmark - Marmosets **BUCTD-W48** (Ours) \*----\*



Ye, S., Lauer, J., Zhou, M., Mathis, A., and Mathis, MW, "AmadeusGPT: a natural language interface" for interactive animal behavioral analysis", NeurIPS, 2023

## **Action understanding**



### Comparison on Marmosets

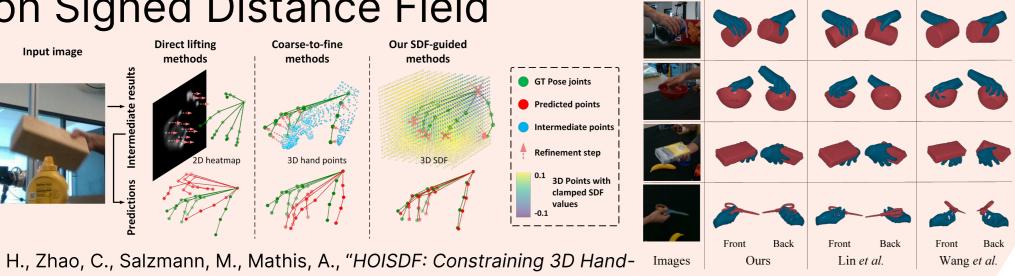


Zhou, M\*., Stoffl, L\*., Mathis, MW., Mathis, A., "Rethinking pose estimation in crowds: overcoming the detection information bottleneck and ambiguity", ICCV, 2023

## **HOISDF:** Hand object pose estimation based

on Signed Distance Field

BUCTD-W48

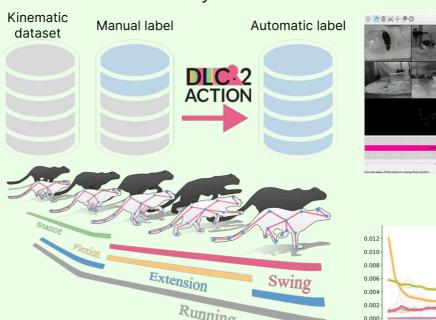


Qi, H., Zhao, C., Salzmann, M., Mathis, A., "HOISDF: Constraining 3D Hand-Object Pose Estimation with Global Signed Distance Fields", CVPR, 2024



# **DLC-2ACTION** What is my cat doing?

body kinematics. Supporting diverse pose data formats, the toolbox allows you to **Y** extract kinematic features and tidily run trainings, evaluations and predictions from a set of supervised **Deep Learning models**. The toolbox is associated with a User Interface to manually annotate actions of interest from videos.

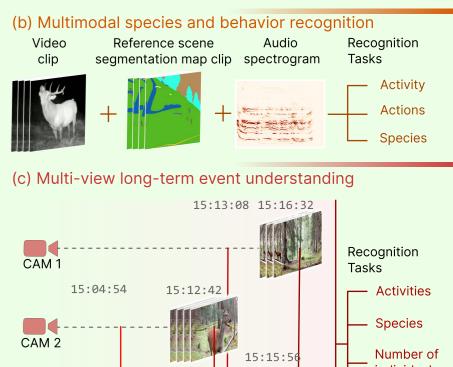


**Boehringer Ingelheim Fonds** 

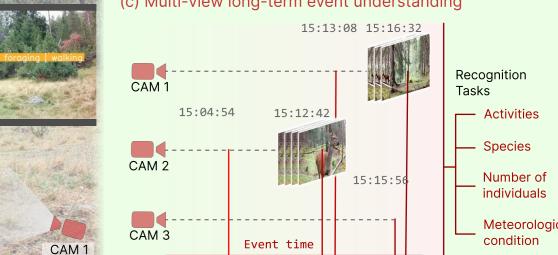
Stiftung für medizinische

Grundlagenforschung

A multimodal and multiview camera trap dataset of wildlife behavior in the Swiss Alps



Demo



**WildCLIP** 

Retrieving events of interest from camera trap images with domain-adapted vision-language models

We create many image-caption pairs...



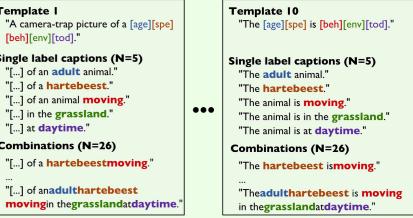
) SimBA-RA

**H**ierarchical

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Sturman OF



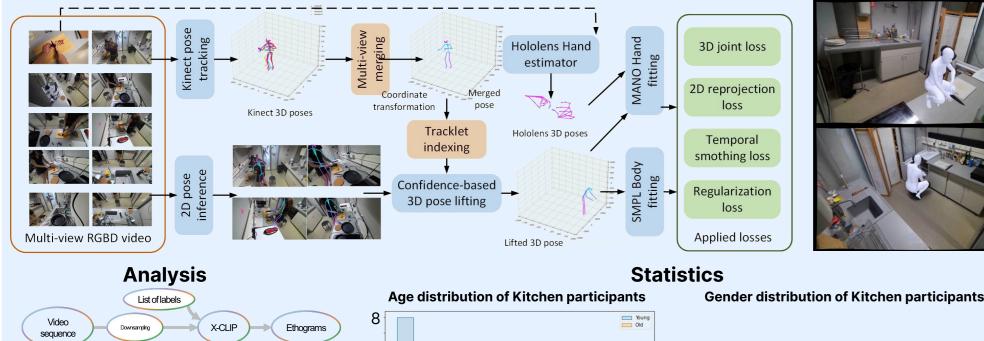


... to retrieve behavioral events corresponding to complex queries.





### C. 3D Human Reconstruction



20

30

Chan

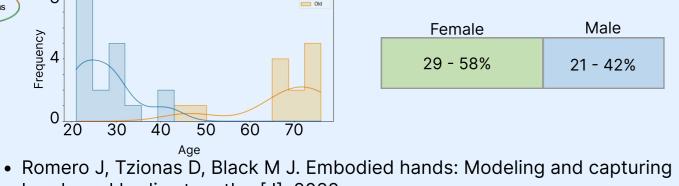
Zuckerberg

Initiative 😚

Preparing

Microsoft AI

naredient



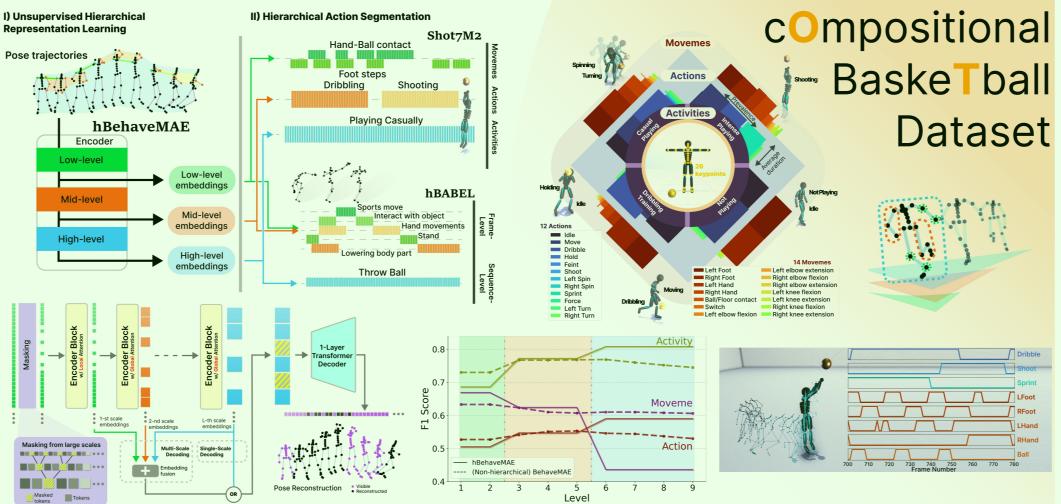
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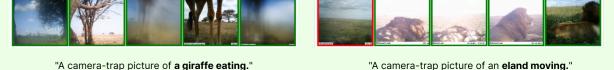
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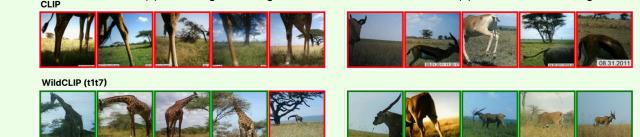
FOUNDATION

hands and bodies together[J]. 2022. • Loper M, Mahmood N, Romero J, et al. SMPL: A skinned multi-person linear model[M]//Seminal Graphics Papers.2023.

Shot7M2: Synthetic **hBehaveMAE**: Learning the hierarchical structure of behavior







Gabeff, V., Russwurm, M., Tuia, D., & Mathis, A. (2023). WildCLIP: Scene and animal attribute retrieval from camera trap data with domain-adapted vision-language models. *International Journal of Computer Vision (in* press)

We love

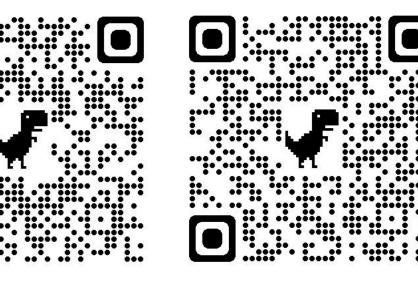




Check out our open source! website!

## **Selected Collaborators:**

Mackenzie Mathis, EPFL Silvestro Micera, EPFL Friedhelm Hummel, EPFL Marc Pollefeys, ETH Antoine Bosselut, EPFL Devis Tuia, EPFL



**Swiss National Science Foundation**