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## Graph diffusion models - DiGress [1]

## Motivation

Build a discrete diffusion model to leverage the inherent discrete nature of graph structures.

## Approach

#### **Discrete diffusion**

- Transition probability is defined through the transition matrix  $\mathbf{Q}_t$  and  $ar{\mathbf{Q}}_t = \mathbf{Q}_1 \cdots \mathbf{Q}_t$
- Adding noise corresponds to sample from a categorical distribution  $q(z_t|z_{t-1}) = z_{t-1}\mathbf{Q}_t$
- Posterior distribution:  $q(z_{t-1}|z_t, x) = z_t \mathbf{Q}_t^\top \odot x \bar{\mathbf{Q}}_{t-1}$



#### **Discrete diffusion for graphs - DiGress**

- Attributed graph with *a* and *b* node/edge classes:  $G = (X \in \mathbb{R}^{n \times a}, E \in \mathbb{R}^{n \times n \times (b+1)})$
- Add graph noise:  $q(G^t|G^{t-1}) = (\mathbf{X}^{t-1}\mathbf{Q}_X^t, \mathbf{E}^{t-1}\mathbf{Q}_E^t)$
- Equivariant model: equivariant architecture + invariant loss

$$l(\hat{p}^G, G) = \sum_{1 \le i \le n} \operatorname{CE}(x_i, \hat{p}_i^X) + \lambda \sum_{1 \le i, j \le n} \operatorname{CE}(e_{ij}, \hat{p}_{ij}^E)$$

- Add extra features to overcome GNN expressive limit
- Promote sparsity with *marginal* noise model



Denoising chain with uniform (top) /marginal (bottom) noise

# Large graph generation - SparseDiff<sup>[2]</sup>

#### **Motivation**

encodings and enable large graph generation.



SparseDiff uses off-the-shell edge list representation

$$G = (\mathbf{E} \in \mathbb{N}^{2 \times m}, \mathbf{X} \in \{0, 1\}^{n \times a}, \mathbf{Y} \in \{0, 1\}^{m \times b})$$

Its *efficient* training consists of 2 components:

- Noise model that preserves the sparsity of noisy graphs
- Sparse denoising network trained on a random subset of node pairs



## Constrained graph generation - ConStruct<sup>[3]</sup>

### **Motivation**

Hard-constrain graph discrete diffusion models using graph **structural properties**.

ConStruct preserves the forward and reverse process in the constrained domain:

- Forward - not learnable, so designed to preserve edgedeletion invariant properties

$$\mathbf{Q}_X^t = \alpha^t \mathbf{I} + (1 - \alpha^t) \mathbf{1}_b \mathbf{m}_X'$$
$$\mathbf{Q}_E^t = \alpha_{ABS}^t \mathbf{I} + (1 - \alpha_{ABS}^t) \mathbf{1}_c \mathbf{e}_E'$$

#### **Denoising process**

- Sample the number of nodes train distribution
- Iterate over T diffusion steps to predict a clean graph

### **Results**



Generated graphs with DiGress

- Reverse - edge insertion process due to forward, but requires *projector* to refuse constraint violating edges



Improved 80% in validity in digital pathology setting



e.g. planarity:  $O(n) \rightarrow O(\alpha(q, n))$ 

References [1] Vignac et al., DiGress: Discrete Denoising diffusion for graph generation, 2023 [2] Qin et al., Sparse Training of Discrete Diffusion Models for Graph Generation, 2023 [3] Madeira et al., Generative Modelling of Structurally Constrained Graphs, 2024